

Chapter One- Part (II)
Vector Analysis and Coordinate Systems

1-1: Introduction:

The use of vectors and vector analysis can greatly simplify the mathematics used in expressing and manipulating the laws and theorems of electric and magnetic fields.

1-2: Scalars and Vectors:

Scalar is a quantity that has only magnitude, such as: **time**, **distance**, temperature, **entropy**, **energy**, **mass**, electric potential

The vector is a quantity that has both magnitude and direction, such as: **velocity**, **force**, **displacement**, **electric and magnetic field intensity**

The vector \vec{A} is denoted in Cartesian coordinate as:

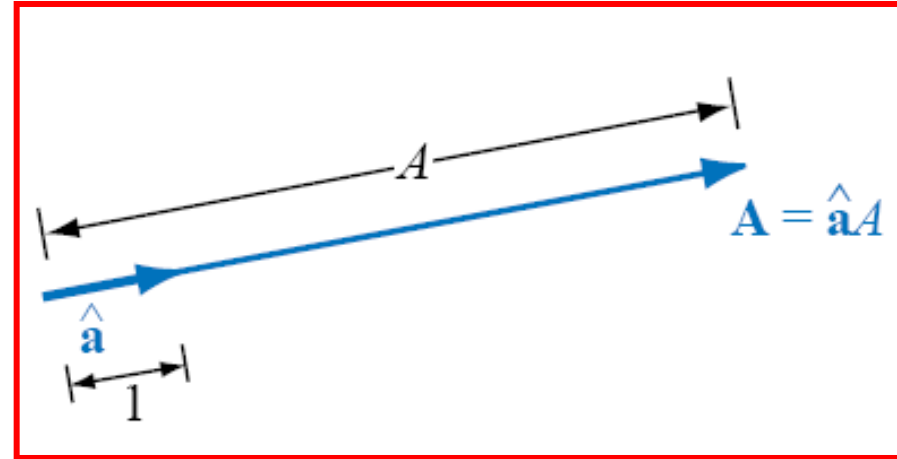
$$\vec{A} = A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z \quad \text{or} \quad \vec{A} = A \hat{a}_a$$

where, \hat{a}_a is a unit vector

1-3: Unit Vectors:

The unit vector of \vec{A} is defined as a vector whose magnitude is unity and its direction is along \vec{A} , that is:

$$\hat{a}_a = \frac{\vec{A}}{|\vec{A}|},$$
$$\vec{A} = A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z$$
$$|\vec{A}| = \sqrt{A_x^2 + A_y^2 + A_z^2}$$



Where, A_x, A_y and A_z are component of \vec{A} in the x, y and z direction respectively.

1-4: Equality of Two Vectors:

The vectors \vec{A} and \vec{B} are said to be equal if they have equal magnitudes and identical unit vectors. Thus, if:

$$\vec{A} = A_x \hat{a}_x + A_y \hat{a}_y + A_z \hat{a}_z \quad \text{or} \quad \vec{A} = A \hat{a}_a$$
$$\vec{B} = B_x \hat{a}_x + B_y \hat{a}_y + B_z \hat{a}_z \quad \text{or} \quad \vec{B} = B \hat{a}_b$$

Then $\vec{A} = \vec{B}$ if and only if $|A| = |B|$ and $\hat{a}_a = \hat{a}_b$

1. When two parallel vectors have the same magnitude and pointing to the same direction are equal.
2. but they are identical only if they lie on top of one another

1-5: Vector addition and subtraction:

Two vectors \vec{A} and \vec{B} can be added together to give another vector \vec{C} that is:

$$\vec{C} = \vec{A} + \vec{B}$$

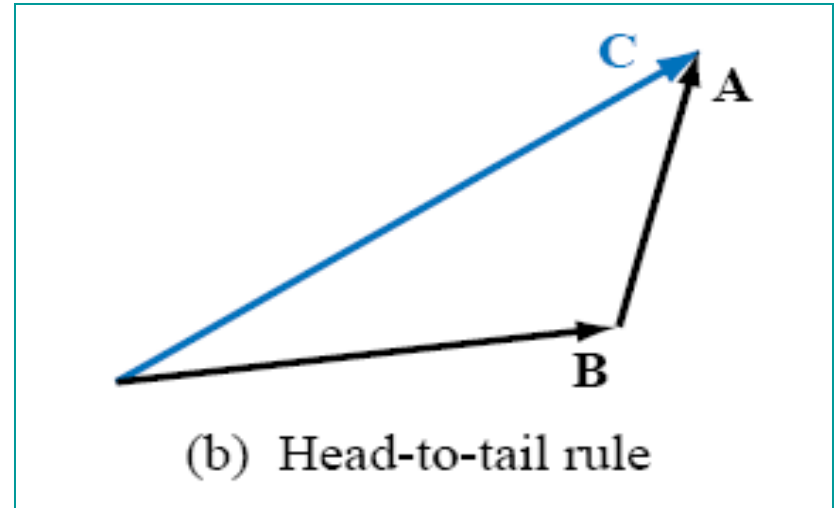
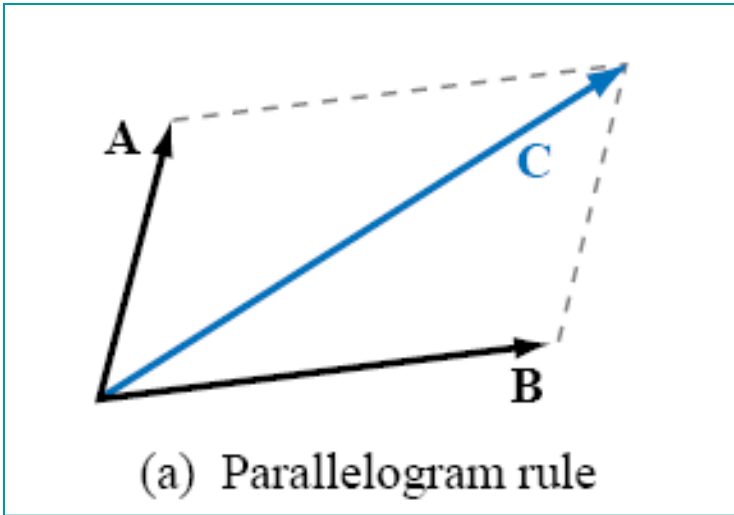
$$\vec{C} = (A_x + B_x)\hat{a}_x + (A_y + B_y)\hat{a}_y + (A_z + B_z)\hat{a}_z$$

$$\vec{C} = C_x\hat{a}_x + C_y\hat{a}_y + C_z\hat{a}_z$$

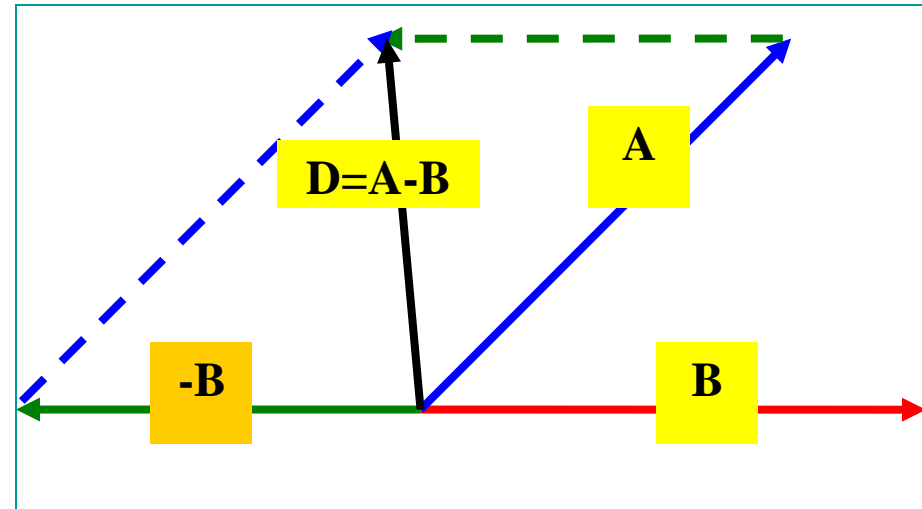
And vector subtraction is similarly carried out as:

$$\vec{D} = \vec{A} - \vec{B} \Rightarrow \vec{D} = (A_x - B_x)\hat{a}_x + (A_y - B_y)\hat{a}_y + (A_z - B_z)\hat{a}_z$$

$$\vec{D} = D_x\hat{a}_x + D_y\hat{a}_y + D_z\hat{a}_z$$



No.	Law	Addition	Multiplication
1.	Commutative	$\vec{A} + \vec{B} = \vec{B} + \vec{A}$	$k \vec{A} = \vec{A} k$
2.	Associative	$\vec{A} + (\vec{B} + \vec{C}) = (\vec{A} + \vec{B}) + \vec{C}$	$k(l \vec{A}) = l(k \vec{A})$
3.	Distributive	$k(\vec{A} + \vec{B}) = k \vec{A} + k \vec{B}$	-----



1-6: Position and Distance Vector:

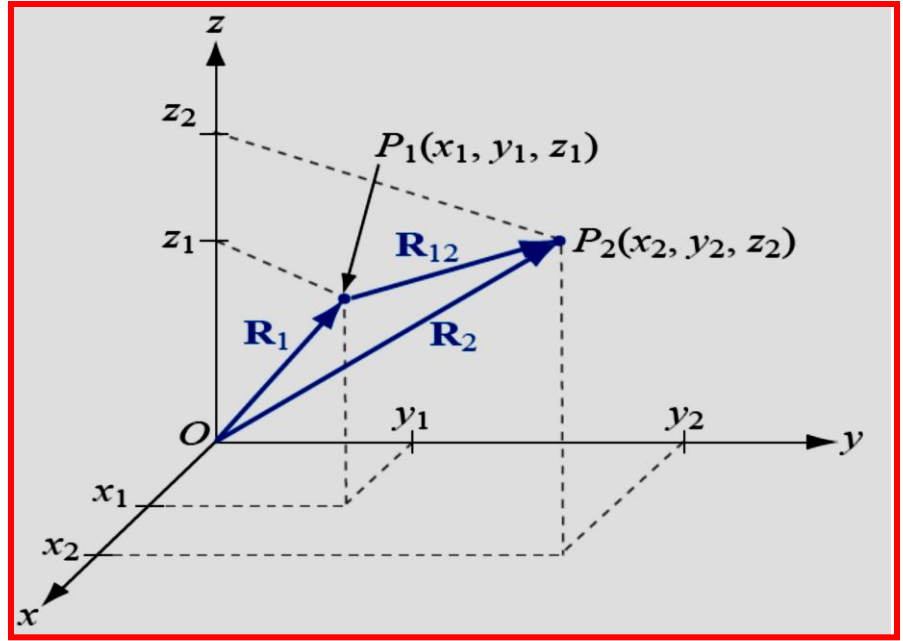
The position vector \vec{R}_p or radius vector of point $P(x, y, z)$ is defined as the directed distance from the origin $O(0,0,0)$ to point

$P(x, y, z)$ as: $\vec{R}_p = \overline{OP} = x\hat{a}_x + y\hat{a}_y + z\hat{a}_z$

The distance vector is the displacement from one point to another, such as, $P_1(x_1, y_1, z_1)$ to $P_2(x_2, y_2, z_2)$ and is represented mathematically as:

$$\vec{R}_{12} = \overline{P_1P_2} = (x_2 - x_1)\hat{a}_x + (y_2 - y_1)\hat{a}_y + (z_2 - z_1)\hat{a}_z$$

Therefore, the position vector is a special case of displacement vector.



Example(1): Given points $P(1,-3,5)$, $Q(2,4,6)$ and $R(0,3,8)$ then find the following:

- (a). the position vectors of P and R (b). the distance vector \vec{r}_{QP} (c). the distance between Q and R

Solution:

(a). $\overline{OP} = (1-0)\hat{a}_x + (-3-0)\hat{a}_y + (5-0)\hat{a}_z = \hat{a}_x + -3\hat{a}_y + 5\hat{a}_z$
 $\overline{OR} = (0-0)\hat{a}_x + (3-0)\hat{a}_y + (8-0)\hat{a}_z = 3\hat{a}_y + 8\hat{a}_z$

(b). $\vec{r}_{QP} = (1-2)\hat{a}_x + (-3-4)\hat{a}_y + (5-6)\hat{a}_z = -\hat{a}_x - 7\hat{a}_y - \hat{a}_z$

(c). $|\overline{QR}| = \sqrt{(0-2)^2 + (3-4)^2 + (8-6)^2} = \sqrt{4+1+4} = 3\text{unit}$

1-7: Vector Multiplication:

Three types of products can occur in vector calculus. These are, simple, scalar(or dot) and vector(or cross) products:

1-7-1: Simple Product:

Multiplication of a vector by a scalar quantity is called a simple product and is represented mathematically as:

$$\vec{A} = A \hat{a}_a$$

$$k \vec{A} = k A \hat{a}_a = \vec{B}$$

$$\vec{B} = k A_x \hat{a}_x + k A_y \hat{a}_y + k A_z \hat{a}_z$$

$$\vec{B} = B_x \hat{a}_x + B_y \hat{a}_y + B_z \hat{a}_z$$

\vec{B} is in the same direction of \vec{A}

Such as $\vec{F}_e = Q \vec{E}$

1-7-2: Scalar Product:

The scalar or dot product of two vectors yields a scalar quantity and is denoted by:

$$\vec{A} \cdot \vec{B} = |A| |B| \cos \theta_{AB}$$

$$W = \int \vec{F} \cdot d\vec{l}$$

$$\vec{A} \cdot (\vec{B} + \vec{C}) = \vec{A} \cdot \vec{B} + \vec{A} \cdot \vec{C}$$

$$\vec{A} \cdot \vec{B} = \vec{B} \cdot \vec{A}$$

$$\vec{A} \cdot \vec{A} = |A|^2 = A^2 = \sqrt{A_x^2 + A_y^2 + A_z^2}$$

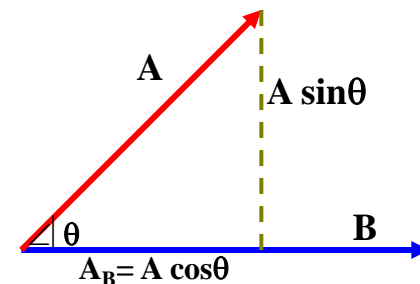
$$\hat{a}_x \cdot \hat{a}_x = \hat{a}_y \cdot \hat{a}_y = \hat{a}_z \cdot \hat{a}_z = 1 \quad \theta_{AB} = 0$$

$$\hat{a}_x \cdot \hat{a}_y = \hat{a}_y \cdot \hat{a}_z = \hat{a}_z \cdot \hat{a}_x = 0 \quad \theta_{AB} = 90$$

And obey the following algebraic relation:

The scalar component of vector \vec{A} along \vec{B} is represented mathematically as:

$$A_B = |A| \cos \theta = \frac{\vec{A} \cdot \vec{B}}{|B|} = \vec{A} \cdot \hat{a}_B$$



and the vector component of \vec{A} along \vec{B} is represented mathematically as:

$$\vec{A}_B = |A| \cos \theta \hat{a}_B = \frac{\vec{A} \cdot \vec{B}}{|B|} \hat{a}_B = (\vec{A} \cdot \hat{a}_B) \hat{a}_B$$

While the normal component of \vec{A} on \vec{B} can be determined as: $\vec{A}_{NB} = \vec{A} - \vec{A}_B$

In addition the scalar projection of vector \vec{A} onto z -axis is given by:

$$A_z = \frac{\hat{a}_z \cdot \vec{A}}{|\hat{a}_z|} = \hat{a}_z \cdot \vec{A}$$

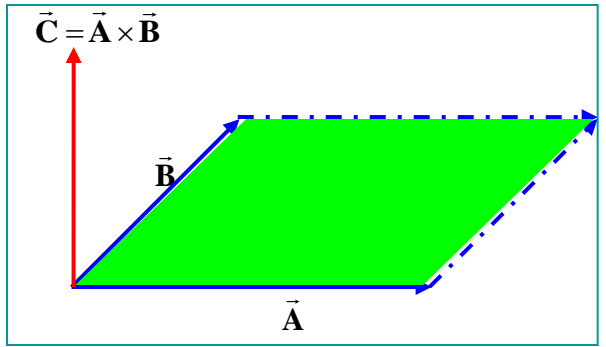
1-7-3: Vector Product:

The vector or cross product of two vectors such as \vec{A} and \vec{B} yields another vector which is perpendicular to both \vec{A} and \vec{B} and is pronounced \vec{A} cross \vec{B} and is denoted by:

$$\vec{A} \times \vec{B} = |\vec{A}| |\vec{B}| \sin \theta = \vec{C} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix} = (A_y B_z - A_z B_y) \hat{a}_x + (A_z B_x - A_x B_z) \hat{a}_y + (A_x B_y - A_y B_x) \hat{a}_z$$

Where \vec{C} is perpendicular to both \vec{A} and \vec{B} . The vector products obey the following algebraic relation:

$$\begin{aligned} \vec{A} \times \vec{B} &= -\vec{B} \times \vec{A} \\ \vec{A} \times (\vec{B} \times \vec{C}) &\neq (\vec{A} \times \vec{B}) \times \vec{C} \\ \vec{A} \times \vec{A} &= \text{zero} \\ \vec{A} \times (\vec{B} \pm \vec{C}) &= \vec{A} \times \vec{B} \pm \vec{A} \times \vec{C} \\ \hat{a}_x \times \hat{a}_x &= \hat{a}_y \times \hat{a}_y = \hat{a}_z \times \hat{a}_z = \text{zero} \\ \hat{a}_x \times \hat{a}_y &= \hat{a}_z & \hat{a}_y \times \hat{a}_z &= \hat{a}_x & \hat{a}_z \times \hat{a}_x &= \hat{a}_y \\ \hat{a}_y \times \hat{a}_x &= -\hat{a}_z & \hat{a}_z \times \hat{a}_y &= -\hat{a}_x & \hat{a}_x \times \hat{a}_z &= -\hat{a}_y \end{aligned}$$



$$\begin{aligned} \vec{\tau} &= \vec{F} \times \vec{r} \\ \vec{F} &= q \vec{v} \times \vec{B} \end{aligned}$$

The magnitude of $\vec{A} \times \vec{B}$ is the area of the parallelogram formed by \vec{A} and \vec{B} as shown in the figure. Therefore, the area of triangular formed by \vec{A} and \vec{B} is $\frac{1}{2} |\vec{A} \times \vec{B}|$

Example(2): Given vectors **determine the following:**

$$\vec{\mathbf{A}} = \hat{a}_x + 3\hat{a}_z$$

$$\text{and } \vec{\mathbf{B}} = 5\hat{a}_x + 2\hat{a}_y - 6\hat{a}_z$$

, then

(a). $|\mathbf{A} + \mathbf{B}|$

(c). the component of

\mathbf{A} along \hat{a}_y

(b). $3\vec{\mathbf{A}} - \vec{\mathbf{B}}$

(d). the unit vector parallel to

$$3\vec{\mathbf{A}} + \vec{\mathbf{B}}$$

Solution:

(a). $\vec{\mathbf{A}} + \vec{\mathbf{B}} = (\hat{a}_x + 3\hat{a}_z) + (5\hat{a}_x + 2\hat{a}_y - 6\hat{a}_z) = 6\hat{a}_x + 2\hat{a}_y - 3\hat{a}_z$

$$|\vec{\mathbf{A}} + \vec{\mathbf{B}}| = \sqrt{36 + 4 + 9} = 7 \text{ unit}$$

(b). $3\vec{\mathbf{A}} - \vec{\mathbf{B}} = (3\hat{a}_x + 9\hat{a}_z) - (5\hat{a}_x + 2\hat{a}_y - 6\hat{a}_z) = -2\hat{a}_x - 2\hat{a}_y + 15\hat{a}_z$

(c). the scalar component of \mathbf{A} along \hat{a}_y is given by:

$$A_y = \vec{\mathbf{A}} \cdot \hat{a}_y = \frac{\vec{\mathbf{A}} \cdot \hat{a}_y}{|\hat{a}_y|} = \frac{(\hat{a}_x + 3\hat{a}_z) \cdot \hat{a}_y}{|\hat{a}_y|} = \frac{0}{1} = 0$$

The vector component of \mathbf{A} along \hat{a}_y is given by:

$$\vec{\mathbf{A}}_y = (\vec{\mathbf{A}} \cdot \hat{a}_y) \hat{a}_y = \frac{\vec{\mathbf{A}} \cdot \hat{a}_y}{|\hat{a}_y|} \hat{a}_y = (0) \hat{a}_y = 0$$

(d). $3\vec{\mathbf{A}} + \vec{\mathbf{B}} = (3\hat{a}_x + 9\hat{a}_z) + (5\hat{a}_x + 2\hat{a}_y - 6\hat{a}_z) = 8\hat{a}_x + 2\hat{a}_y + 3\hat{a}_z$, then the unit vector parallel to

this vector is calculated as:

$$\hat{a}_{3\vec{\mathbf{A}} + \vec{\mathbf{B}}} = \frac{3\vec{\mathbf{A}} + \vec{\mathbf{B}}}{|3\vec{\mathbf{A}} + \vec{\mathbf{B}}|} = \frac{8\hat{a}_x + 2\hat{a}_y + 3\hat{a}_z}{\sqrt{64 + 4 + 9}} = \frac{8\hat{a}_x + 2\hat{a}_y + 3\hat{a}_z}{\sqrt{77}}$$

Example(3): Derive the cosine formula $c^2 = a^2 + b^2 + 2ab \cos \theta$ **and the sine**

formula

$$\frac{\sin a}{a} = \frac{\sin b}{b} = \frac{\sin c}{c}$$

using dot and cross product respectively.

Cosine formula:

$$\vec{c} = \vec{a} + \vec{b}$$

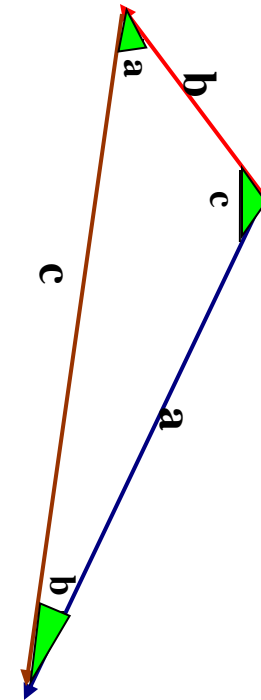
$$\vec{c} \cdot \vec{c} = (\vec{a} + \vec{b}) \cdot (\vec{a} + \vec{b}) = a^2 + b^2 + 2\mathbf{a} \cdot \mathbf{b}$$

$$c^2 = a^2 + b^2 + 2ab \cos \theta \quad \Rightarrow \quad c = \sqrt{a^2 + b^2 + 2ab \cos \theta}$$

Sine formula:

$$\left| \frac{1}{2} \vec{a} \times \vec{b} \right| = \left| \frac{1}{2} \vec{b} \times \vec{c} \right| = \left| \frac{1}{2} \vec{c} \times \vec{a} \right|$$

$$\therefore \frac{1}{2} a b \sin c = \frac{1}{2} b c \sin a = \frac{1}{2} c a \sin b$$



dividing the above equation by (a b c) we get :

$$\frac{\sin c}{c} = \frac{\sin a}{a} = \frac{\sin b}{b}$$

Example(4): Let $\vec{E} = 3\hat{a}_y + 4\hat{a}_z$ and $\vec{F} = 4\hat{a}_x - 10\hat{a}_y + 5\hat{a}_z$, then find:

(a). the component of \vec{E} along \vec{F} (b). A unit vector perpendicular to both \vec{E} and \vec{F}

Solution:

(a). the vector component of \vec{E} along \vec{F} is given by:

$$\begin{aligned}\vec{E}_F &= |\vec{E}| \cos \theta \hat{a}_F = \frac{\vec{E} \cdot \vec{F}}{|\vec{F}|} \hat{a}_F = (\vec{E} \cdot \hat{a}_F) \hat{a}_F \\ \hat{a}_F &= \frac{4\hat{a}_x - 10\hat{a}_y + 5\hat{a}_z}{\sqrt{16 + 100 + 25}} = \frac{4\hat{a}_x - 10\hat{a}_y + 5\hat{a}_z}{\sqrt{141}} \\ \therefore (\vec{E} \cdot \hat{a}_F) \hat{a}_F &= \left[(3\hat{a}_y + 4\hat{a}_z) \cdot \frac{4\hat{a}_x - 10\hat{a}_y + 5\hat{a}_z}{\sqrt{141}} \right] \frac{4\hat{a}_x - 10\hat{a}_y + 5\hat{a}_z}{\sqrt{141}} \\ \therefore \vec{E}_F &= \frac{(12 + 20)}{141} (4\hat{a}_x - 10\hat{a}_y + 5\hat{a}_z)\end{aligned}$$

The scalar component of \vec{E} along \vec{F} is given by:

$$\begin{aligned}\vec{E}_F &= |\vec{E}| \cos \theta = \frac{\vec{E} \cdot \vec{F}}{|\vec{F}|} = \vec{E} \cdot \hat{a}_F \\ \vec{E}_F &= \vec{E} \cdot \hat{a}_F = \left[(3\hat{a}_y + 4\hat{a}_z) \cdot \frac{4\hat{a}_x - 10\hat{a}_y + 5\hat{a}_z}{\sqrt{141}} \right] = \frac{12 + 20}{\sqrt{141}}\end{aligned}$$

1-8: Scalar and Vector Triple Product:

When three vectors are multiplied, not all combinations of dot or cross products are meaningful. For example the product: $\vec{A} \times (\vec{B} \cdot \vec{C})$, $(\vec{A} \times \vec{B}) \vec{C}$ not defined under the rules of algebra.

Therefore, the only two meaningful products of three vectors are the **Scalar triple** and the **Vector product** as represented them below:

1-8-1: Scalar Triple Product:

A scalar triple product denoted $\vec{A} \cdot (\vec{B} \times \vec{C})$ and obeying the following cyclic order:

$$\vec{A} \cdot (\vec{B} \times \vec{C}) = \vec{C} \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\vec{C} \times \vec{A})$$

where,

$$\vec{A} \cdot (\vec{B} \times \vec{C}) = \begin{vmatrix} A_x & A_y & A_z \\ B_x & B_y & B_z \\ C_x & C_y & C_z \end{vmatrix}$$

1-8-2: Vector Triple Product:

The vector triple product involves the cross product of a vector with the cross product of two others, such as:

$$\vec{A} \times (\vec{B} \times \vec{C}) \neq (\vec{A} \times \vec{B}) \times \vec{C}$$

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{C}(\vec{A} \cdot \vec{B}) \text{ very important rule----prove this (H. W.)}$$

Example(5): Three field quantities are given by:
 $\vec{R} = 2\hat{a}_x - 3\hat{a}_y + \hat{a}_z$ determine the following:

$$\vec{P} = 2\hat{a}_x - \hat{a}_z, \quad \vec{Q} = 2\hat{a}_x - \hat{a}_y + 2\hat{a}_z$$

- (a). $(\vec{P} + \vec{Q}) \times (\vec{P} - \vec{Q}) = \vec{P} \times (\vec{P} - \vec{Q}) + \vec{Q} \times (\vec{P} - \vec{Q})$ (b). $\vec{Q} \cdot (\vec{R} \times \vec{P})$ (c). $\sin \theta_{QR}$
 (d). $\vec{P} \times (\vec{Q} \times \vec{R})$ (e). A unit vector perpendicular to both \vec{Q} and \vec{R}

Solution: $(\vec{P} + \vec{Q}) \times (\vec{P} - \vec{Q}) = \vec{P} \times (\vec{P} - \vec{Q}) + \vec{Q} \times (\vec{P} - \vec{Q}) = \vec{P} \times \vec{P} - \vec{P} \times \vec{Q} + \vec{Q} \times \vec{P} - \vec{Q} \times \vec{Q}$

(a).

$$= 0 + \vec{Q} \times \vec{P} + \vec{Q} \times \vec{P} - 0 = 2|\vec{P}||\vec{Q}| \sin \theta_{QP}$$

$$|\vec{P}| = \sqrt{4+1} = \sqrt{5} \quad |\vec{Q}| = \sqrt{4+1+4} = 3$$

$$\theta_{QP} = \cos^{-1} \frac{\vec{Q} \cdot \vec{P}}{|\vec{P}||\vec{Q}|} = \frac{4-2}{3 \times \sqrt{5}} = \frac{2}{3\sqrt{5}} = 72.65^\circ$$

$$\sin 72.65 = 0.95$$

(b).

$$\vec{Q} \cdot (\vec{R} \times \vec{P}) = \begin{vmatrix} 2 & -1 & 2 \\ 2 & -3 & 1 \\ 2 & 0 & -1 \end{vmatrix} = 2 \times (3 - 0) - 1 \times (2 + 2) + 2 \times (0 + 6) = 6 - 4 + 12 = 14$$

(c).

$$\sin \theta_{QR} = \frac{|\vec{Q} \times \vec{R}|}{|\vec{Q}||\vec{R}|} \quad \vec{Q} \times \vec{R} = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ 2 & -1 & 2 \\ 2 & -3 & 1 \end{vmatrix} = \hat{a}_x(-1+6) + \hat{a}_y(4-2) + \hat{a}_z(-6+2) = 5\hat{a}_x + 2\hat{a}_y - 4\hat{a}_z$$

$$|\vec{Q} \times \vec{R}| = \sqrt{25+4+16} = \sqrt{45}, \quad |\vec{Q}| = \sqrt{4+1+4} = 3 \quad \text{and} \quad |\vec{R}| = \sqrt{4+9+1} = \sqrt{14}$$

$$\sin \theta_{QR} = \frac{\sqrt{45}}{3\sqrt{14}} = 0.596$$

$$(d). \quad \vec{P} \times (\vec{Q} \times \vec{R}) = \begin{vmatrix} \hat{a}_x & \hat{a}_y & \hat{a}_z \\ 2 & 0 & -1 \\ 5 & 2 & -4 \end{vmatrix} = \hat{a}_x (0+2) + \hat{a}_y (-5+8) + \hat{a}_z (4-0) = 2\hat{a}_x + 3\hat{a}_y + 4\hat{a}_z$$

$$(e). \quad \hat{a}_{QR} = \frac{\vec{Q} \times \vec{R}}{|\vec{Q}| |\vec{R}|} = \frac{5\hat{a}_x + 2\hat{a}_y - 4\hat{a}_z}{3\sqrt{14}}$$

(f). The scalar and vector component of \vec{P} along \vec{Q} can be calculated as follows:

The scalar component of \vec{P} along \vec{Q} is equal to: $\vec{P}_Q = |\vec{P}| \cos \theta = \frac{\vec{P} \cdot \vec{Q}}{|\vec{Q}|} = \vec{P} \cdot \hat{a}_Q$

$$\vec{P} \cdot \hat{a}_Q = \left[(2\hat{a}_x - \hat{a}_z) \cdot \frac{2\hat{a}_x - \hat{a}_y + 2\hat{a}_z}{3} \right] = \frac{4-2}{3} = \frac{2}{3}$$

The vector component of \vec{P} along \vec{Q} is given by:

$$\vec{P}_Q = |\vec{P}| \cos \theta \hat{a}_Q = \frac{\vec{P} \cdot \vec{Q}}{|\vec{Q}|} \hat{a}_Q = (\vec{P} \cdot \hat{a}_Q) \hat{a}_Q$$

$$\hat{a}_Q = \frac{2\hat{a}_x - \hat{a}_y + 2\hat{a}_z}{3}$$

$$\therefore (\vec{P} \cdot \hat{a}_Q) \hat{a}_Q = \left[(2\hat{a}_x - \hat{a}_z) \cdot \frac{2\hat{a}_x - \hat{a}_y + 2\hat{a}_z}{3} \right] \frac{2\hat{a}_x - \hat{a}_y + 2\hat{a}_z}{3}$$

$$\therefore \vec{P}_Q = \frac{4-2}{9} (2\hat{a}_x - \hat{a}_y + 2\hat{a}_z) = \frac{2}{9} (2\hat{a}_x - \hat{a}_y + 2\hat{a}_z)$$

Home Work

Q1/ Given $\vec{A} = \hat{a}_x - \hat{a}_y$, $\vec{B} = 2\hat{a}_z$ and $\vec{C} = -\hat{a}_x + 3\hat{a}_y$, find both $\vec{A} \cdot \vec{B} \times \vec{C}$ and $(\vec{A} \times \vec{B}) \times \vec{C}$

Q2 / Show that : $(\vec{A} \cdot \vec{B})^2 + (\vec{A} \times \vec{B})^2 = (AB)^2$

Q3 / Find the triple scalar and vector product of the following vectors :

$$\vec{P} = 2\hat{a}_x - 2\hat{a}_y + \hat{a}_z, \quad \vec{Q} = \hat{a}_x + \hat{a}_y + \hat{a}_z \quad \text{and} \quad \vec{R} = 2\hat{a}_x + 3\hat{a}_z$$

Q4/ Find the angle between $\vec{A} = 10\hat{a}_y + 2\hat{a}_z$, and $\vec{B} = -4\hat{a}_y + 0.5\hat{a}_z$
using both dot and cross product.

Q5/ Given $\vec{A} = (y-1)\hat{a}_x + 2x\hat{a}_y$, find the vector at point $(2,2,1)$ and its projection

on vector \vec{B} where $\vec{B} = 5\hat{a}_x - \hat{a}_y + 2\hat{a}_z$

Q6/ Given vectors $\vec{A} = \hat{a}_x + 2\hat{a}_y - 3\hat{a}_z$, $\vec{B} = 3\hat{a}_x - 4\hat{a}_y$ and $\vec{C} = 3\hat{a}_y - 4\hat{a}_z$

find the following :

- a. $|\vec{A}|$ and \hat{a}_A b. the component of \vec{B} along \vec{C} c. θ_{AC} d. $\vec{A} \times \vec{C}$
- e. $\vec{A} \times (\vec{B} \times \vec{C})$ f. $\hat{a}_x \times \vec{B}$ g. $(\vec{A} \times \hat{a}_y) \cdot \hat{a}_z$ h. $\vec{A} \cdot (\vec{B} \times \vec{C})$

Q7/ Express the unit vector directed toward the point $(0,0,h)$ from an arbitrary point in the plane $z = -2$. Explain the result as $h = -2$?

Q8/ Given $\vec{A} = 4\hat{a}_y + 10\hat{a}_z$ and $\vec{B} = 2\hat{a}_x + 3\hat{a}_y$, find the magnitude and vector components of \vec{A} on \vec{B} ?

Q9 /Given Vectors $\vec{T} = 2\hat{a}_x - 6\hat{a}_y + 3\hat{a}_z$ and $\vec{S} = \hat{a}_x + 2\hat{a}_y + \hat{a}_z$ then find the following :

(a)- The scalar projection of \vec{T} on \vec{S} (b)-The vector projection of \vec{S} on \vec{T}

(c)- The angle between \vec{T} and \vec{S}