

Chapter seven

Magnetostatic field

7-1: Introduction and History:

In the previous chapters, we have studied the electric charges and the fields they produce, which are \vec{E}, \vec{D} and ∇ . We also shown that moving charges gives rise to the electric current concept.

In this chapter, we shall find that a current will produce a magnetic field that will in turn produce a force on magnetic material, magnets and other current configurations. We shall also show that the magnetic monopole can not be isolated in the same manner as electric charges .

In this chapter we focus our attention to the static magnetic fields, which characterize by

\vec{H} – magnetic Field Intensity (A/m)

\vec{B} – Magnetic Flux Density (Tesla)

$$\mathbf{B} = \mu \mathbf{H} \quad \text{like} \quad \mathbf{D} = \epsilon \mathbf{E}$$

$$\text{for free space } \mu = \mu_0 = 4\pi \times 10^{-7} \text{ (H/m)}$$

- 1- **ca. BC 600**, In northern Greece, a shepherd named Magnus experiences a pull on the iron nails in his sandals by the black rock he was standing on. The region was later named **Magnesia** and the rock became known as magnetite [a form of iron with permanent magnetism Fe_3O_4].
- 2- **ca. 1000**, Magnetic compass used as a navigational device
- 3- **1820 Hans Christian Oersted (1777-1851)(Danish) after (13) years** of experiments study and efforts, demonstrates the interconnection between electricity and magnetism through his discovery that an electric current in a wire causes a compass needle to orient itself perpendicular to the wire.
- 4- **1821 Andre-Marie Ampere (French)** notes that parallel currents in wires attract each other and opposite currents repel.
- 5- **1821 Jean-Baptiste Biot (French) and Felix Savart (French)** develop the Biot-Savart law relating the magnetic field induced by a wire segment to the current flowing through it.
- 6- **1827 Joseph Henry (American)** introduces the concept of inductance and built one of the earliest electric motors. He also assisted Samuel Morse in the development of the telegraph.
- 7- **1831 Michael Faraday (English)** discovers that a changing magnetic flux can induce an electromotive force.

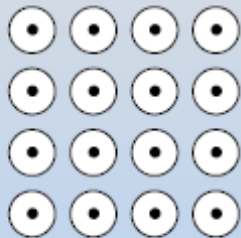
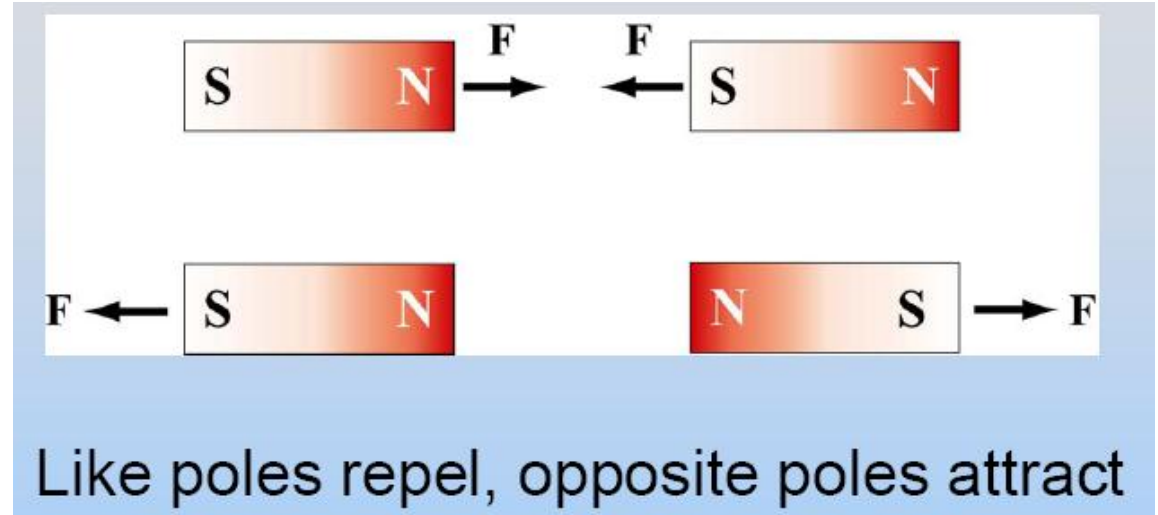
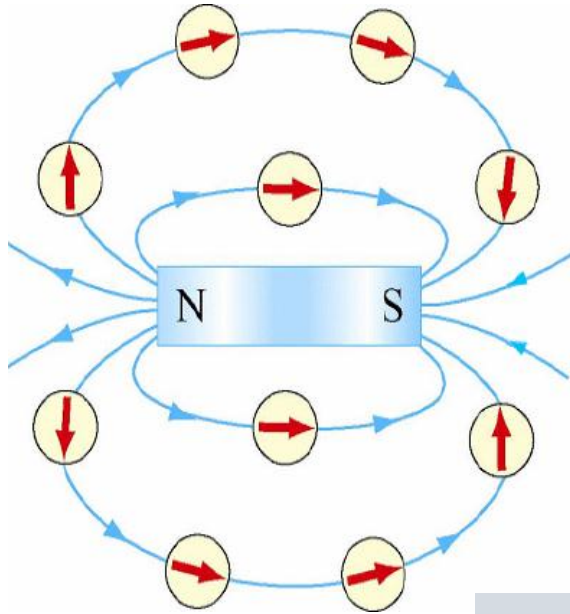
7-2: Sources and Applications of Magnetic Field:

The magnetic field can be produced due to one of the following sources:

- 1- Permanent magnetic material**
- 2- Moving charge with constant velocity (or steady current)**
- 3- Time varying electric fields.**

The magnetic fields are used in most of the electric devices such as the following:

- 1- Motors**
- 2- Transformers**
- 3- Microphone**
- 4- Telephone bell rings**
- 5- Television control focusing**
- 6- Memory store**
- 7- Magnetically levitated high-speed vehicles**



OUT of page
“Arrow Head”



INTO page
“Arrow Tail”

7-3: Magnetic Force:

- The electric field (\mathbf{E}) at a point in space has been defined as the electric force (\mathbf{F}_e) per unit charge acting on test charge when placed at that point .

$$\vec{\mathbf{F}}_e = q \vec{\mathbf{E}}$$

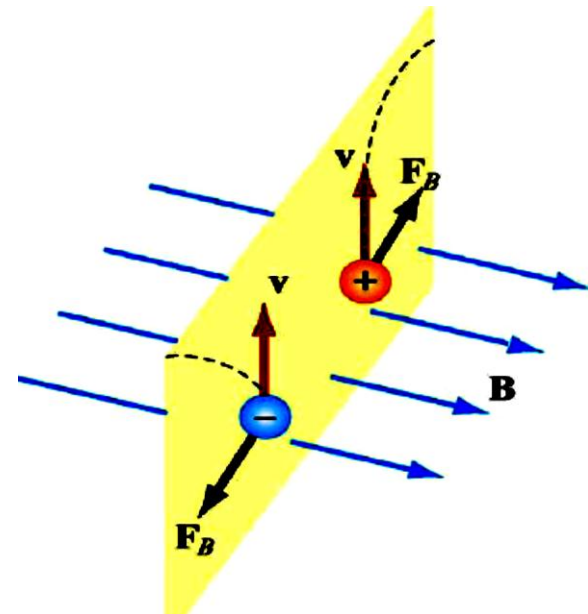
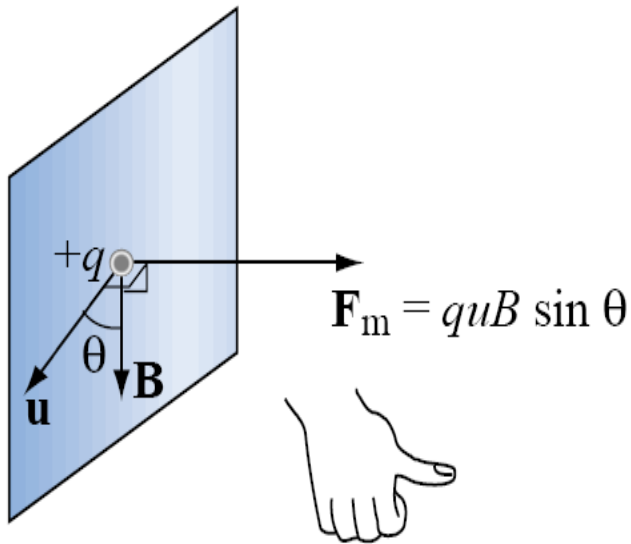
- We now define the magnetic flux density (\mathbf{B}) at a point in space in terms of the magnetic force (\mathbf{F}_m) that would exerted on a charged particle moving with a velocity (\mathbf{u}) were it to be passing through that point.

$$\vec{\mathbf{F}}_m = q \vec{\mathbf{u}} \times \vec{\mathbf{B}} \quad \text{where} \quad \mathbf{B} \text{ is measure in unit of } (N s / C m) = N / A m = \text{Tesla}$$

and $1 T = 10^4 \text{ Gauss}$

$$\mathbf{F}_m = q \mathbf{u} \mathbf{B} \sin \theta \quad \text{where } \theta \text{ is the angle between } \mathbf{u} \text{ and } \mathbf{B}$$

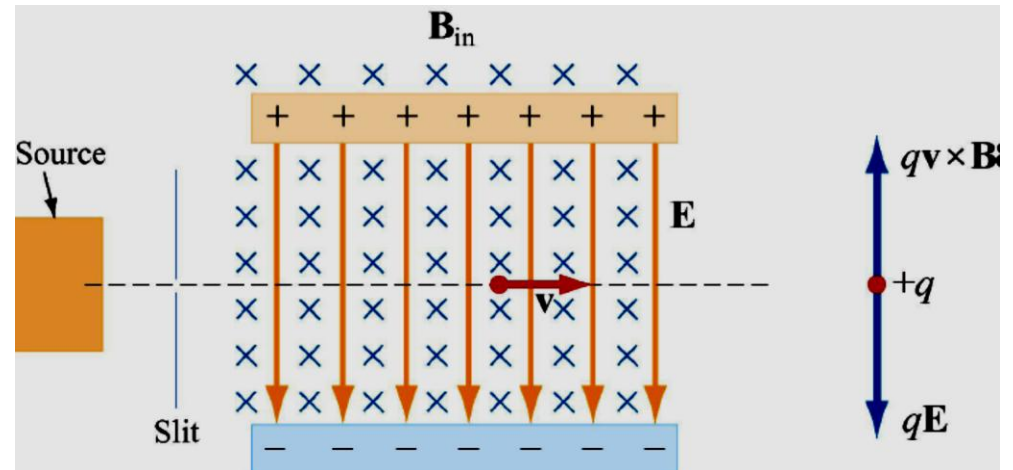
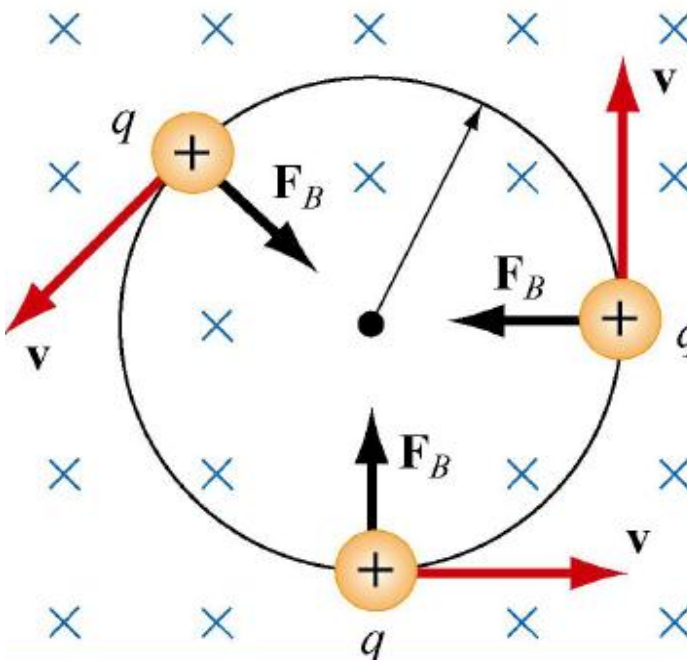
- We note that (F_m) is maximum when (u) is perpendicular to (B) ($\theta = 90^\circ$), and it is zero when (u) is parallel to (B) ($\theta = 0^\circ, 180^\circ$).
- For a positively charged particle, the direction of (F_m) is in the direction of cross product ($\vec{u} \times \vec{B}$), which is perpendicular to the plane containing (u and B) and governed by the right hand rule. If (q) is negative, the direction of (F_m) is reversed as illustrated below. The magnitude of (F_m) is given by:



When a charge particle moving with a constant velocity (\mathbf{u}) and entered to a region contain a constant uniform magnetic field is experienced by a force due to the magnetic field and make it to move in a circular motion as shown below:

If a charged particle is in the presence of both an electric field (\mathbf{E}) and a magnetic field (\mathbf{B}), then the total electromagnetic force acting on it is:

$$\vec{\mathbf{F}} = \vec{\mathbf{F}}_e + \vec{\mathbf{F}}_m = q(\vec{\mathbf{E}} + \vec{\mathbf{u}} \times \vec{\mathbf{B}})$$



Particle moves in a straight line when

$$\vec{\mathbf{F}}_{net} = q(\vec{\mathbf{E}} + \vec{\mathbf{v}} \times \vec{\mathbf{B}}) = 0 \Rightarrow v = \frac{E}{B}$$

Fundamental Differences between electric & Magnetic Forces

1- Whereas the electric force (F_e) is always in the direction of the electric field (E), the magnetic force (F_m) is always perpendicular to the magnetic field (B).

2- Whereas the electric force (F_e) acts on a charged particle whether or not it is moving, the magnetic force (F_m) acts on it only when it is in motion.

3- Whereas the electric force (F_e) expends energy in displacing a charged particle the magnetic force (F_m) does no work when a particle is displaced.

7-3-1: Magnetic Force on a Current Carrying Conductor:

A current flowing through a conducting wire consists of charged particles drifting through the material of the wire. Consequently, when a current-carrying wire is placed in a magnetic field, it will experience a force equal to the sum of the magnetic forces acting on the charged particles moving within it. Therefore, the magnetic force for a current-carrying wire can be expressed as:

$$d\vec{F}_m = dq \vec{u} \times \vec{B} \quad \text{and} \quad dq = \rho_v dv$$

$$\text{where } \rho_v = Ne \quad \text{and} \quad dv = Adl$$

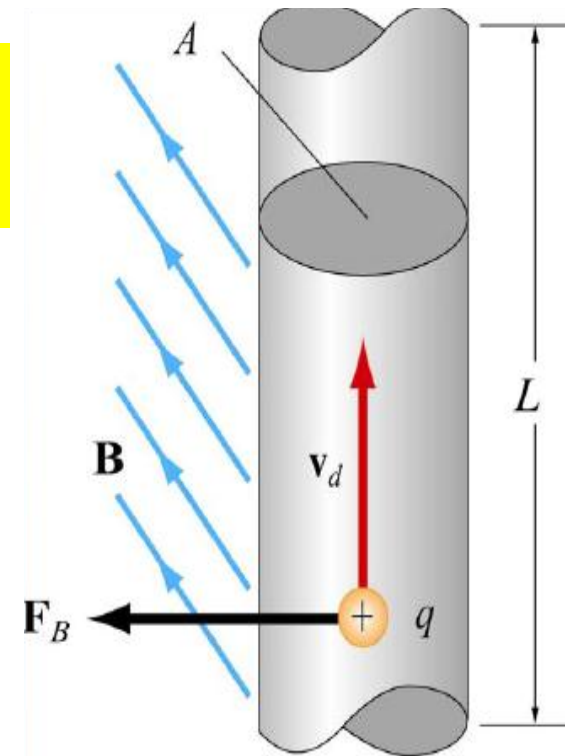
$$d\vec{F} = NeAu_d d\vec{l} \times \vec{B}$$

$$\text{where } \vec{J} = \rho_v u_d = Ne u_d$$

$$\text{and } I = JA$$

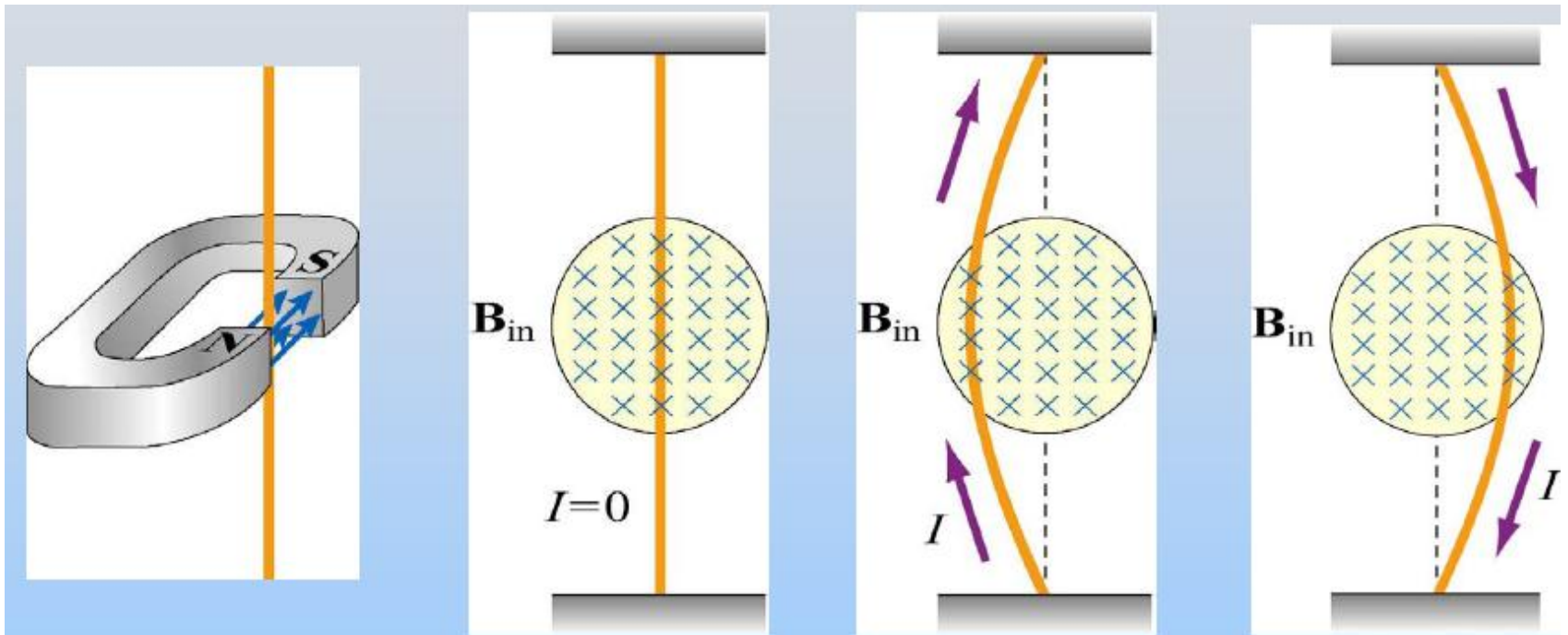
$$\therefore d\vec{F} = I d\vec{l} \times \vec{B}$$

$$\frac{d\vec{F}_m}{dq} = \vec{u} \times \vec{B} = \vec{E}$$



Therefore, for a regular segment of conducting wire of length (L) and carrying current (I) , the magnetic force can be expressed as:

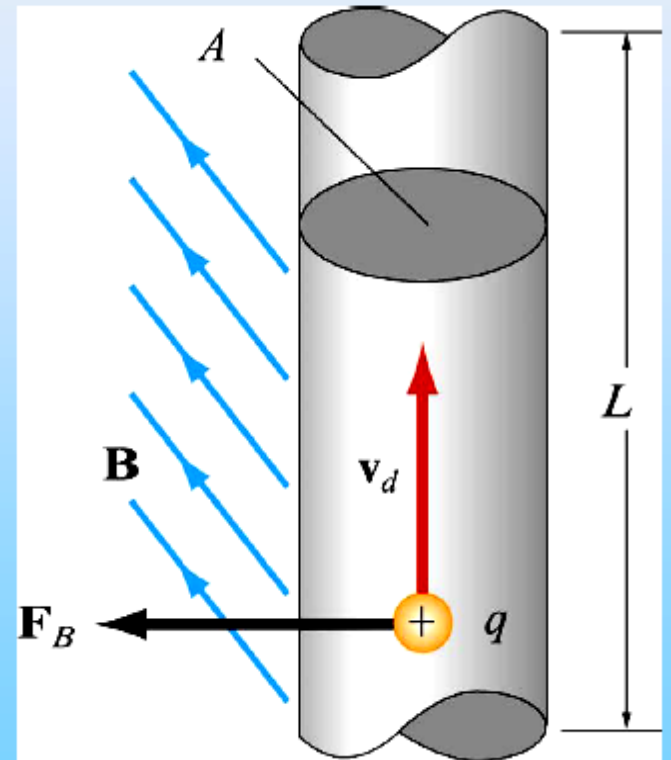
$$\vec{F}_m = I \vec{L} \times \vec{B} \Rightarrow \Rightarrow F_m = I L B \sin \theta$$



Current is moving charges, and we know that moving charges **feel** a force in a magnetic field

$$\begin{aligned}
 \vec{\mathbf{F}}_B &= q\vec{\mathbf{v}} \times \vec{\mathbf{B}} \\
 &= (\text{charge}) \frac{\text{m}}{\text{s}} \times \vec{\mathbf{B}} \\
 &= \frac{\text{charge}}{\text{s}} \text{m} \times \vec{\mathbf{B}}
 \end{aligned}$$

$$\vec{\mathbf{F}}_B = I (\vec{\mathbf{L}} \times \vec{\mathbf{B}})$$



Examples

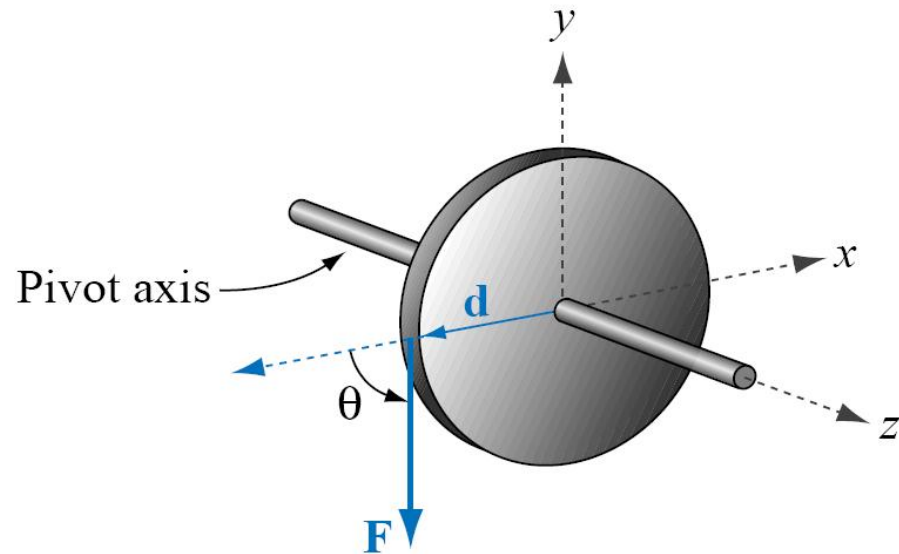
A (10 nC) charge particle has a velocity $\vec{v} = 3 \hat{a}_x + 4 \hat{a}_y + 5 \hat{a}_z \text{ (m/s)}$ as it enters a magnetic field $\vec{B} = 1000 \hat{a}_y \text{ (T)}$. Calculate the force vector on the charge and what electric field is required so that the velocity of the charged particle remains constant.

7-3-2: Magnetic Torque on a Current –Carrying Loop

When a force is applied on a rigid body pivoted about a fixed axis, the body will react by rotating about that axis. The strength of the reaction depends on the cross product of the applied force vector (\mathbf{F}) and the distance vector (\mathbf{d}), measured from a point on the rotation axis (such that \mathbf{d} is perpendicular to the axis) to the point of application (\mathbf{F}), see figure below:

The length of (\mathbf{d}) is called the **moment arm** and the cross product of (\mathbf{d}) with (\mathbf{F}) is called the **Torque**:

$$\vec{\mathbf{T}} = \vec{\mathbf{d}} \times \vec{\mathbf{F}}$$



To demonstrate the Torque which produces by a magnetic force, consider a rectangular loop of rigid wires carrying current (\mathbf{I}) and has a dimensions (\mathbf{a}) and (\mathbf{b}) placed in a constant uniform magnetic field (\mathbf{B}) as shown below:

According to the equation:

$$\vec{\mathbf{F}}_m = I \vec{\mathbf{L}} \times \vec{\mathbf{B}} \Rightarrow \Rightarrow \mathbf{F}_m = I L \mathbf{B} \sin \theta$$

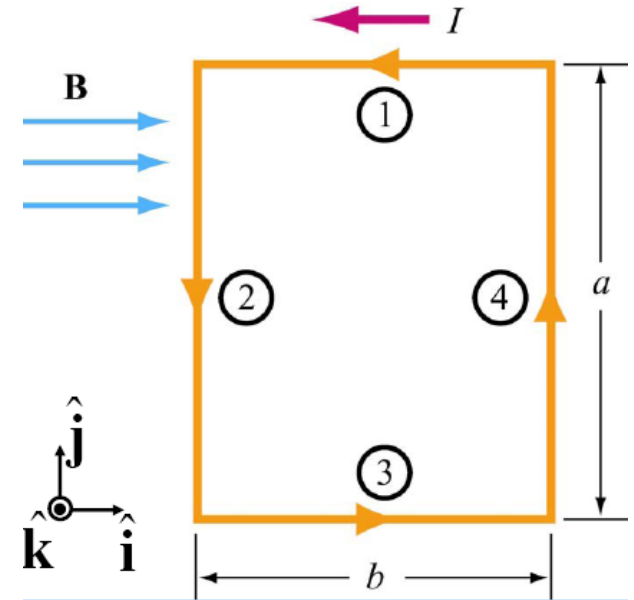
$$\vec{\mathbf{F}}_1 = \vec{\mathbf{F}}_3 = 0 \quad (\mathbf{I} \vec{\mathbf{L}} \parallel \vec{\mathbf{B}})$$

$$\vec{\mathbf{F}}_2 = I (-a \hat{\mathbf{a}}_y) \times \mathbf{B} \hat{\mathbf{a}}_x = I a \mathbf{B} \hat{\mathbf{a}}_z$$

$$\vec{\mathbf{F}}_4 = I (a \hat{\mathbf{a}}_y) \times \mathbf{B} \hat{\mathbf{a}}_x = -I a \mathbf{B} \hat{\mathbf{a}}_z$$

$$\vec{\mathbf{F}}_T = \vec{\mathbf{F}}_1 + \vec{\mathbf{F}}_2 + \vec{\mathbf{F}}_3 + \vec{\mathbf{F}}_4 = 0$$

No net force on the loop



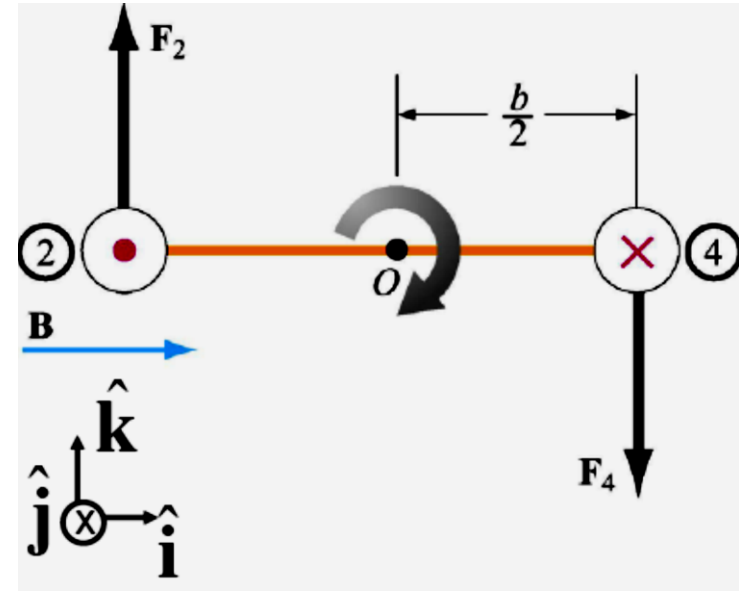
Torque on rectangular loop

$$\vec{\mathbf{T}} = \vec{\mathbf{r}} \times \vec{\mathbf{F}}$$

$$\vec{\mathbf{T}} = \left(-\frac{b}{2} \hat{a}_x\right) \times \vec{\mathbf{F}}_2 + \left(\frac{b}{2} \hat{a}_x\right) \times \vec{\mathbf{F}}_4$$

$$\vec{\mathbf{T}} = \left(-\frac{b}{2} \hat{a}_x\right) \times (\mathbf{I} a \mathbf{B} \hat{a}_z) + \left(\frac{b}{2} \hat{a}_x\right) \times (-\mathbf{I} a \mathbf{B} \hat{a}_z)$$

$$\vec{\mathbf{T}} = \frac{\mathbf{I} a b \mathbf{B}}{2} \hat{a}_y + \frac{\mathbf{I} a b \mathbf{B}}{2} \hat{a}_y = \mathbf{I} a b \mathbf{B} \hat{a}_y$$



Therefore, the magnetic torque on this loop can be expressed as:

$$\vec{\mathbf{T}} = \mathbf{I} \mathbf{A} \mathbf{B} \hat{a}_y \quad \vec{\mathbf{A}} = \mathbf{A} \hat{a}_n = \mathbf{a} \mathbf{b} \hat{a}_n \quad \text{area vector of the loop}$$

since: $\vec{\mathbf{B}} = \mathbf{B} \hat{a}_x$ hence; $\hat{a}_n = \hat{a}_z$ in this example

$$\vec{\boldsymbol{\tau}} = I \vec{\mathbf{A}} \times \vec{\mathbf{B}}$$

Familiar? No net force but there is a torque

Magnetic Dipole Moment

Magnetic dipole moment of a current loop is defined as the product of the current through the loop and the area of the loop, directed normal to the plane of the current loop

$$\vec{\mathbf{m}} = I \mathbf{A} \hat{\mathbf{a}}_n = I \vec{\mathbf{A}}$$

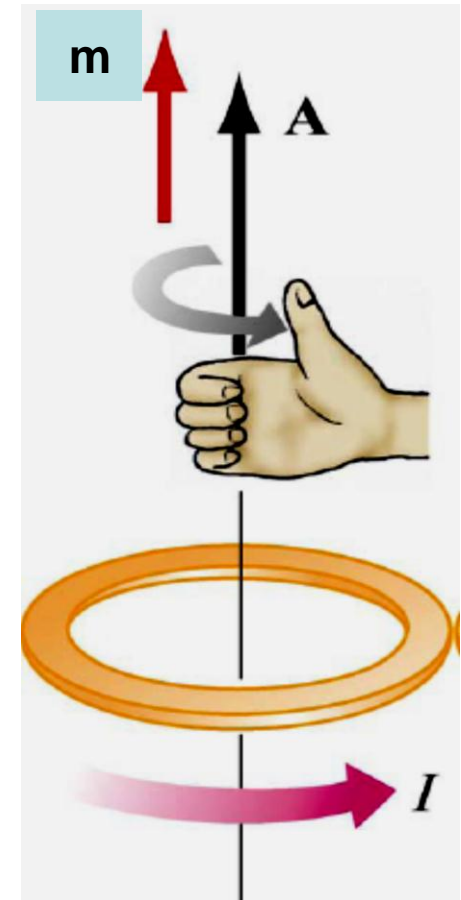
for a loop with N – turns

$$\vec{\mathbf{m}} = N I \vec{\mathbf{A}}$$

Then:
$$\vec{\mathbf{T}} = \vec{\mathbf{m}} \times \vec{\mathbf{B}}$$

analogous to
$$\vec{\mathbf{T}} = \vec{\mathbf{p}} \times \vec{\mathbf{E}}$$

\mathbf{T} tends to align \mathbf{m} with \mathbf{B}



Examples

A circular current loop of radius (r) and current (I) lies in the $z = 0$ - plane. Find the torque which results if the current is in the \hat{a}_ϕ - direction and there is a uniform magnetic field $\vec{B} = \frac{B_0}{\sqrt{2}}(\hat{a}_x + \hat{a}_z)$. Ans. $\frac{\pi r^2 B_0 I}{\sqrt{2}} \hat{a}_y$

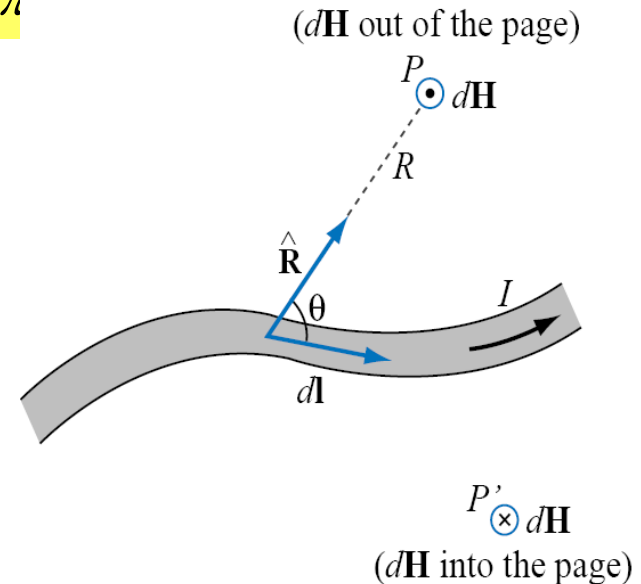
7-4: Biot-Savart's Law:

The **Biot-Savart's** law, states that] The differential magnetic field intensity ($d\mathbf{H}$) produced at a point (\mathbf{P}) by the differential current element ($I d\mathbf{l}$) is directly proportional to the product of ($I d\mathbf{l}$) and the sine of the angle between the current element and the line joining (\mathbf{P}) to the element and is inversely proportional to the square of the distance (\mathbf{R}) between (\mathbf{P}) and the element. That is:

$$d\vec{\mathbf{H}} = \frac{i d\vec{\mathbf{l}} \times \hat{\mathbf{a}}_R}{4\pi R^2} \Rightarrow \Rightarrow \text{where} \quad \mathbf{B} = \mu \mathbf{H} \quad \Rightarrow \Rightarrow d\vec{\mathbf{B}} = \frac{\mu_0 i d\vec{\mathbf{l}} \times \hat{\mathbf{a}}_R}{4\pi R^2}$$

$i d\vec{\mathbf{l}}$ = is called *filamentary current* (A.m)

R = Distance between ($i d\mathbf{l}$) and point \mathbf{P}

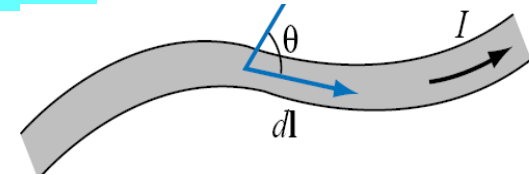


$$\hat{\mathbf{a}}_R = \text{Unit vector} = \frac{\vec{\mathbf{R}}}{|\vec{\mathbf{R}}|}$$

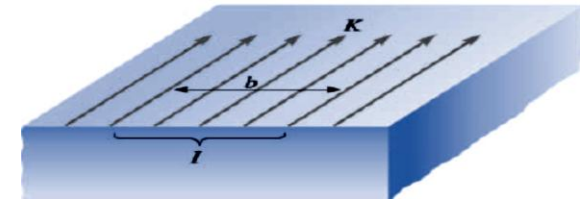
$$\mu_0 = \text{Magnetic permeability of free space} = 4\pi \times 10^{-7} \text{ (H / m)}$$

There are three types of current configurations, they are

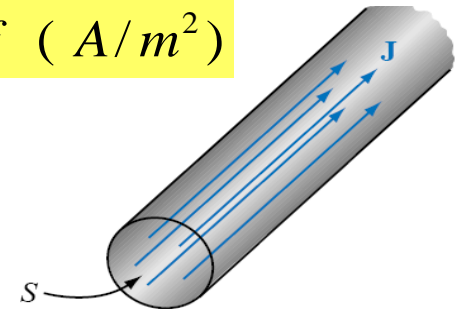
1. Line current density (filamentary Current) $(i d\vec{l})$



2. Surface Current Density $(\vec{K} ds)$ \mathbf{K} measure in unit of (A/m)



3. Volume Current density $(\vec{J} dv)$ \mathbf{J} measure in unit of (A/m^2)



$$i dl = k ds = J dv$$

$$\text{and hence } \vec{\mathbf{B}} = \frac{\mu_0 i d\vec{l} \times \hat{a}_R}{4\pi \mathbf{R}^2} = \frac{\mu_0 \vec{K} ds \times \hat{a}_R}{4\pi \mathbf{R}^2} = \frac{\mu_0 \vec{\mathbf{J}} \times \hat{a}_R dv}{4\pi \mathbf{R}^2}$$

Therefore, the magnetic field for each of the current configurations can be integrally expressed as:

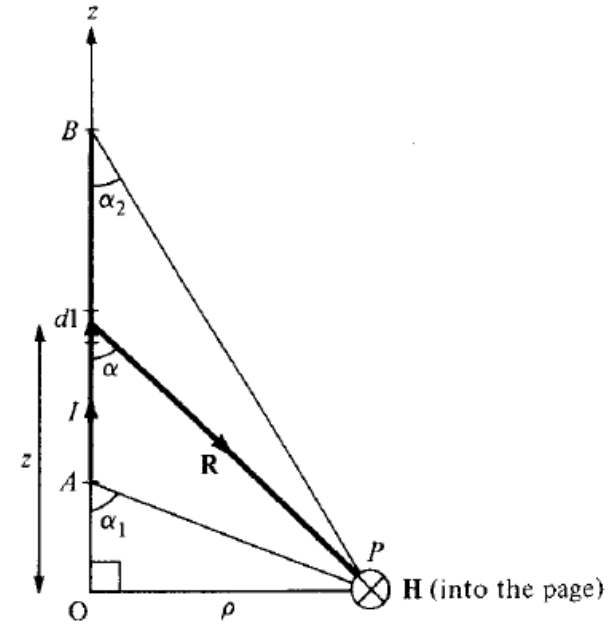
$$\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \int \frac{i d\vec{l} \times \hat{a}_R}{\mathbf{R}^2} \quad \text{for filamentary current distribution}$$

$$\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \int \frac{\vec{K} \times \hat{a}_R}{\mathbf{R}^2} ds \quad \text{for surface current distribution}$$

$$\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \int \frac{\vec{\mathbf{J}} \times \hat{a}_R}{\mathbf{R}^2} dv \quad \text{for volume current distribution}$$

Example (1): A linear conductor of length (L) and carrying a current (I) is placed along the Z-axis as shown in figure below. Determine the magnetic flux density (B) at a point (P) located at a distance (ρ) in the (x-y)-plane in free space.

$$\vec{\mathbf{B}} = \frac{\mu_o}{4\pi} \int \frac{i d\vec{\mathbf{l}} \times \hat{\mathbf{a}}_R}{\mathbf{R}^2}$$



$$i d\vec{\mathbf{l}} = i dz \hat{\mathbf{a}}_z \quad \vec{\mathbf{R}} = \rho \hat{\mathbf{a}}_\rho - z \hat{\mathbf{a}}_z \quad \hat{\mathbf{a}}_R = \frac{\vec{\mathbf{R}}}{|\vec{\mathbf{R}}|} = \frac{\rho \hat{\mathbf{a}}_\rho - z \hat{\mathbf{a}}_z}{\sqrt{\rho^2 + z^2}}$$

$$i d\vec{\mathbf{l}} \times \hat{\mathbf{a}}_R = i dz \hat{\mathbf{a}}_z \times \frac{\rho \hat{\mathbf{a}}_\rho - z \hat{\mathbf{a}}_z}{\sqrt{\rho^2 + z^2}} = \frac{i \rho dz}{\sqrt{\rho^2 + z^2}} \hat{\mathbf{a}}_\phi$$

$$\vec{\mathbf{B}} = \frac{\mu_0}{4\pi} \int \frac{i \rho dz}{(\rho^2 + z^2)^{3/2}} \hat{a}_\phi = \frac{\mu_0 i \rho}{4\pi} \int \frac{dz}{(\rho^2 + z^2)^{3/2}} \hat{a}_\phi$$

$$z = \rho \cot \alpha \quad \text{then} \quad dz = \rho \operatorname{cosec}^2 \alpha d\alpha$$

$$\text{and hence, } \rho^2 + z^2 = \rho^2 (1 + \cot^2 \alpha) = \rho^2 \operatorname{cosec}^2 \alpha$$

$$\vec{\mathbf{B}} = \frac{\mu_0 i \rho}{4\pi} \int \frac{\rho \operatorname{cosec}^2 \alpha d\alpha}{(\rho^2 \operatorname{cosec}^2 \alpha)^{3/2}} \hat{a}_\phi$$

$$\Rightarrow \Rightarrow \frac{\mu_0 i \rho}{4\pi} \int \frac{\rho \operatorname{cosec}^2 \alpha d\alpha}{\rho^3 \operatorname{cosec}^3 \alpha} \hat{a}_\phi$$

$$= \frac{\mu_0 i}{4\pi \rho} \int \sin \alpha d\alpha \hat{a}_\phi$$

$$\begin{aligned}
\vec{\mathbf{B}} &= \frac{\mu_0 i}{4\pi\rho} \int \sin\theta \, d\theta \, \hat{a}_\phi = \frac{\mu_0 i}{4\pi\rho} \hat{a}_\phi (\cos\theta) \\
&= \frac{\mu_0 i}{4\pi\rho} \hat{a}_\phi \left(\frac{z}{\sqrt{\rho^2 + z^2}} \right) \Big|_{-l/2}^{l/2} \\
&= \frac{\mu_0 i}{4\pi\rho} \hat{a}_\phi \left(\frac{l/2}{\sqrt{\rho^2 + l^2/4}} - \frac{-l/2}{\sqrt{\rho^2 + l^2/4}} \right) \\
\vec{\mathbf{B}} &= \frac{\mu_0 i l}{2\pi\rho} \frac{\hat{a}_\phi}{\sqrt{4\rho^2 + l^2}}
\end{aligned}$$

For an infinitely long wire such that $l \gg \rho$, this equation reduces to:

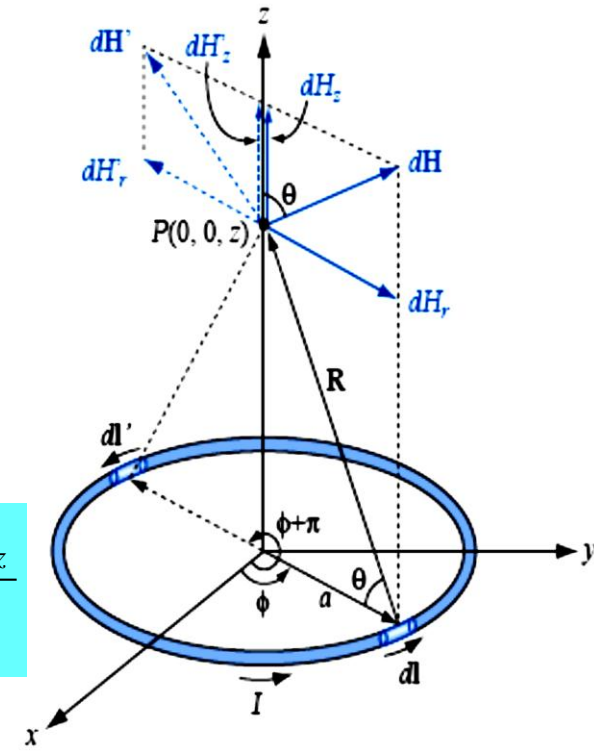
$$\vec{\mathbf{B}} = \frac{\mu_0 i}{2\pi\rho} \hat{a}_\phi = \frac{\mu_0 i}{2\pi r} \hat{a}_\phi = \frac{\mu_0 i}{2\pi d} \hat{a}_\phi ,$$

Where, (r), (d) and (ρ) are the distance from the wire carrying current and the point (P) at which magnetic field is measured.

Example (2): A circular loop of radius (ρ) placed on the ($Z = zero$)-plane and carries a steady current (I). Determine the magnetic flux density (B) at a point on the axis of the loop.

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{i d\vec{l} \times \hat{a}_R}{R^2}$$

$$i d\vec{l} = i \rho d\phi \hat{a}_\phi \quad \vec{R} = -\rho \hat{a}_\rho + z \hat{a}_z \quad \hat{a}_R = \frac{\vec{R}}{|\vec{R}|} = \frac{-\rho \hat{a}_\rho + z \hat{a}_z}{\sqrt{\rho^2 + z^2}}$$



$$i d\vec{l} \times \hat{a}_R = i \rho d\phi \hat{a}_\phi \times \frac{-\rho \hat{a}_\rho + z \hat{a}_z}{\sqrt{\rho^2 + z^2}} = \frac{i \rho (\rho \hat{a}_z + z \hat{a}_\rho) d\phi}{\sqrt{\rho^2 + z^2}}$$

But, due to symmetry about ρ -coordinate the \hat{a}_ρ components of magnetic field are vanishes or cancel each other .

$$\vec{\mathbf{B}} = \frac{\mu_o}{4\pi} \int \frac{i \rho^2 d\phi}{(\rho^2 + z^2)^{3/2}} \hat{a}_z = \frac{\mu_o i \rho^2}{4\pi} \frac{2\pi}{(\rho^2 + z^2)^{3/2}} \hat{a}_z$$

$$\vec{\mathbf{B}} = \frac{\mu_o i \rho^2}{2(\rho^2 + z^2)^{3/2}} \hat{a}_z$$

Therefore, the magnetic flux density of a circular loop at the center of the loop $z=0$, is given by:

$$\vec{\mathbf{B}} = \frac{\mu_o i}{2\rho} \hat{a}_z \quad \text{and} \quad \text{for } N\text{-turn loop} \quad \vec{\mathbf{B}} = \frac{\mu_o N i}{2\rho} \hat{a}_z$$

7-5 : Magnetic Force between Two Parallel Conductors

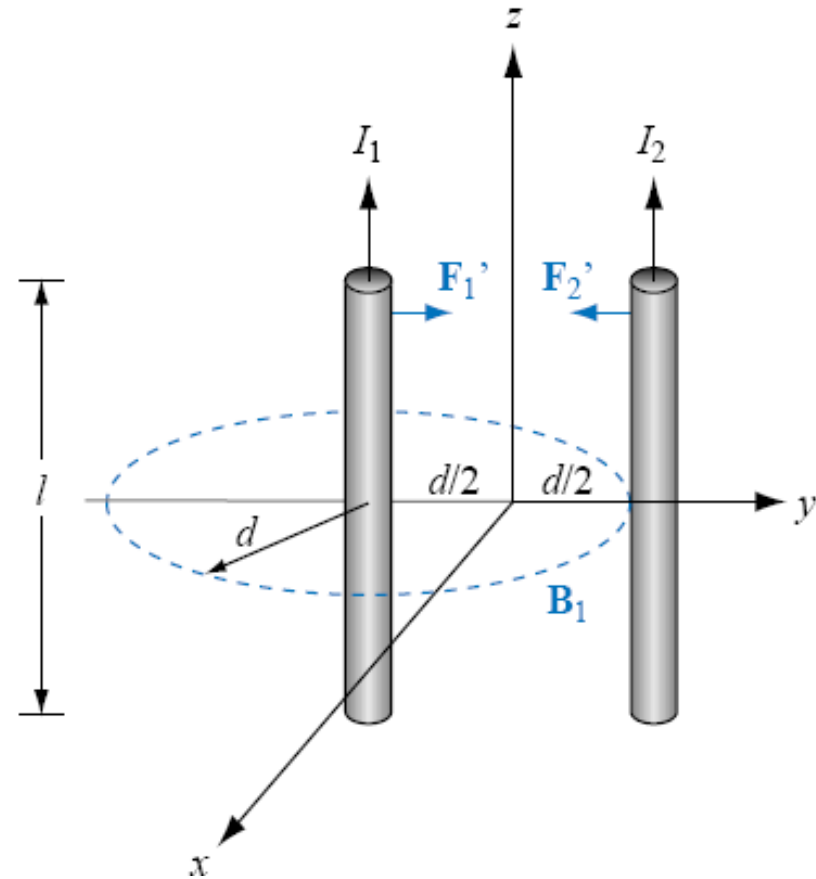
Let us consider two very long (or effectively infinitely long), straight , parallel wires in free space, separated by a distance **(d)** , and carrying currents **(I₁)** and **(I₂)** in the same direction, as shown in figure below.

Current (I₁) is located at $y = -d/2$, and current (I₂) is located at $y = d/2$ and both point in the z-direction.

$$\vec{\mathbf{B}} = \frac{\mu_0 I}{2\pi r} \hat{a}_\phi$$

For the wire carrying current (I₁) ,the magnetic field at distance (d) is given by:

$$\vec{\mathbf{B}}_1 = \frac{\mu_0 I_1}{2\pi d} (-\hat{a}_x) \text{-----(1)}$$



Then the magnetic force (\mathbf{F}_2) exerted on a length (L) of wire carrying current (I_2) due to its presence in field (\mathbf{B}_1) may be obtained by applying the following equation:

$$\vec{\mathbf{F}}_2 = I_2 l \hat{a}_z \times \vec{\mathbf{B}}_1 \Rightarrow I_2 l \hat{a}_z \times \frac{\mu_o I_1}{2 \pi d} (-\hat{a}_x)$$

$$\vec{\mathbf{F}}_2 = \frac{\mu_o I_1 I_2 l}{2 \pi d} (-\hat{a}_y) \text{-----}(2)$$

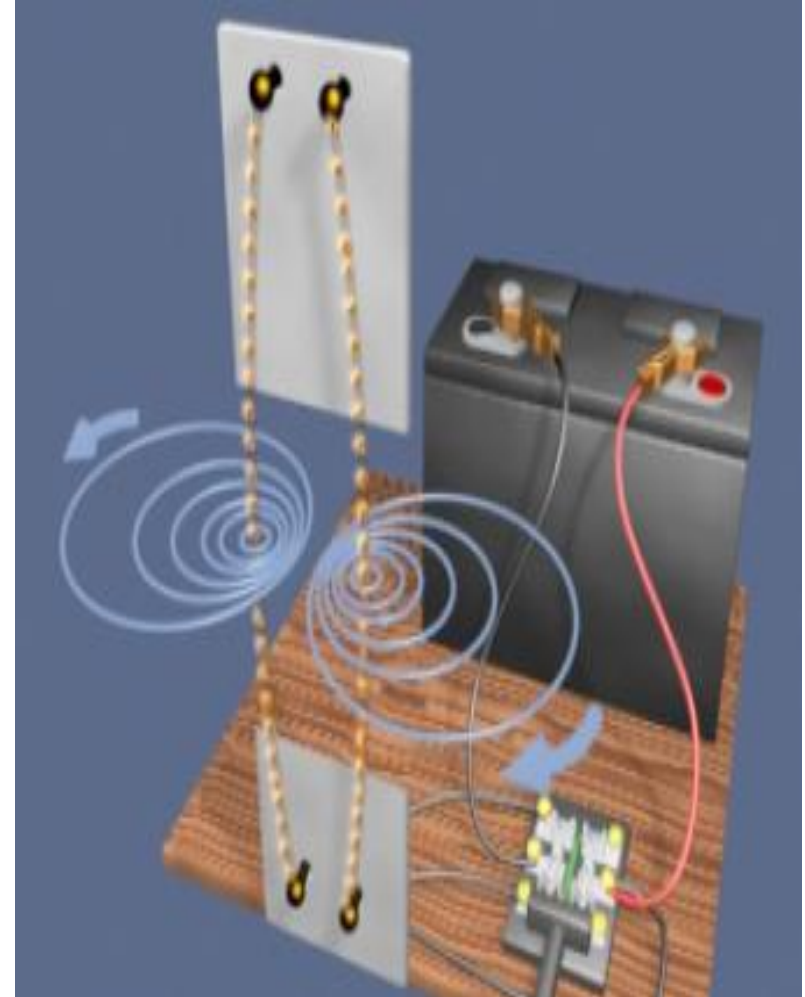
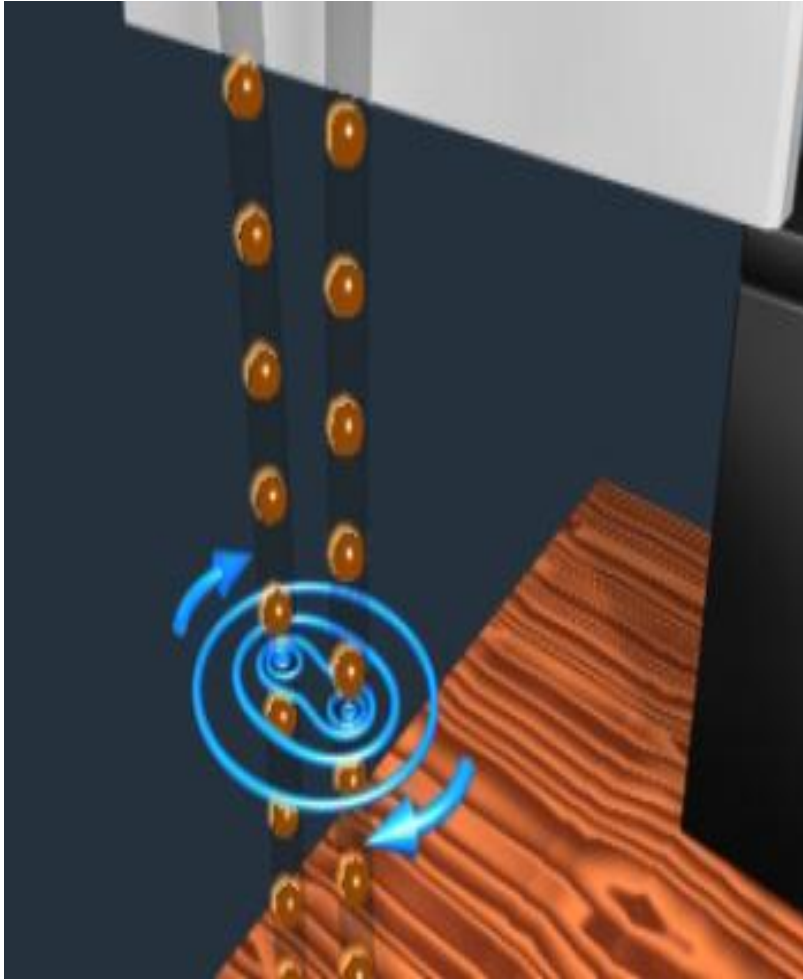
And the corresponding force per unit length is:

$$\vec{\mathbf{F}}'_2 = \frac{\mathbf{F}_2}{l} = \frac{\mu_o I_1 I_2}{2 \pi d} (-\hat{a}_y) \text{-----}(3)$$

A similar analysis performed for the force per unit length exerted on the wire carrying current (I_1) leads to;

$$\vec{\mathbf{F}}'_1 = \frac{\mathbf{F}_1}{l} = \frac{\mu_o I_1 I_2}{2 \pi d} \hat{a}_y \text{-----}(4)$$

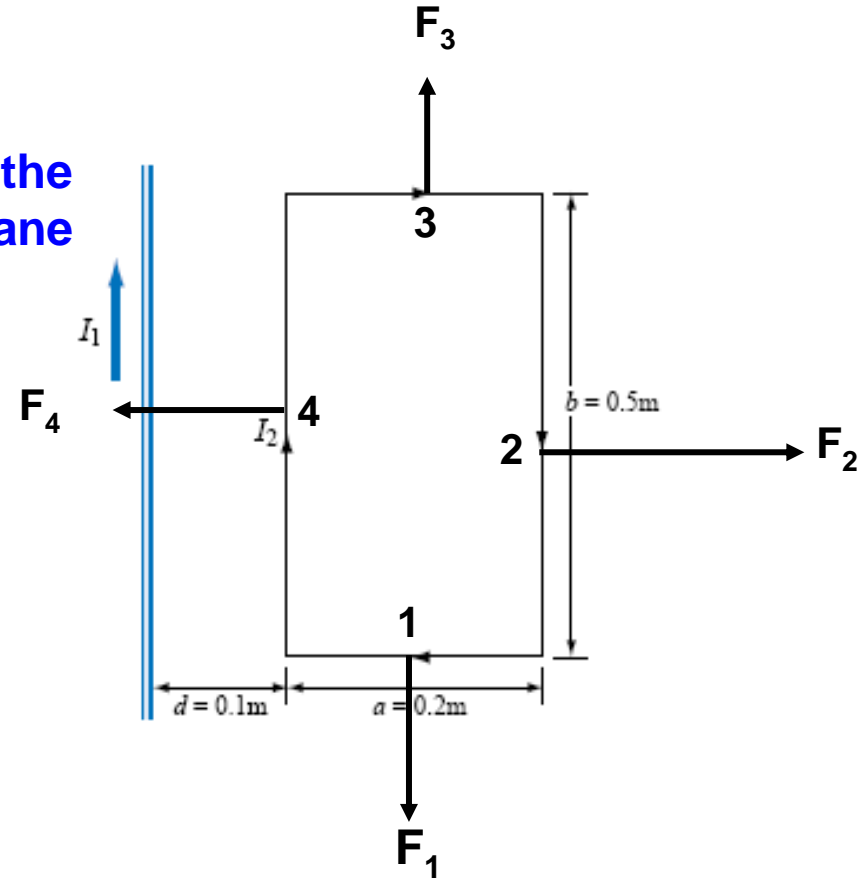
Thus, $F_1 = -F_2$, which means that the two wires attract each other with equal forces. If the currents are in opposite directions, the wires would repel each other with equal forces.



Example(3): The long, straight conductor shown below, lies in the plane of the rectangular loop at a distance ($d= 0.1 \text{ m}$). The loop has dimensions ($a= 0.2 \text{ m}$) and ($b= 0.5 \text{ m}$), and the currents are ($I_1= 10 \text{ A}$) and ($I_2= 15 \text{ A}$). Determine the net magnetic force acting on the loop.

The magnetic field that produces by the straight wire carrying current (I_1) at the plane containing the rectangular loop is given by:

$$\vec{B}_1 = \frac{\mu_o I_1}{2\pi r} (-\hat{a}_x)$$



Then the magnetic force exerted by this field on the individual dimensions of the loop is calculated as:

$$\vec{F}_1 = \mathbf{I}_2 a (-\hat{a}_y) \times \frac{\mu_o \mathbf{I}_1}{2\pi(d+a/2)} (-\hat{a}_x) = \frac{\mu_o a \mathbf{I}_2 \mathbf{I}_1}{2\pi(d+a/2)} (-\hat{a}_z) \text{-----(1)}$$

$$\vec{F}_2 = \mathbf{I}_2 b (-\hat{a}_z) \times \frac{\mu_o \mathbf{I}_1}{2\pi(d+a)} (-\hat{a}_x) = \frac{\mu_o b \mathbf{I}_2 \mathbf{I}_1}{2\pi(d+a)} (\hat{a}_y) \text{-----(2)}$$

$$\vec{F}_3 = \mathbf{I}_2 a (\hat{a}_y) \times \frac{\mu_o \mathbf{I}_1}{2\pi(d+a/2)} (-\hat{a}_x) = \frac{\mu_o a \mathbf{I}_2 \mathbf{I}_1}{2\pi(d+a/2)} (\hat{a}_z) \text{-----(3)}$$

$$\vec{F}_4 = \mathbf{I}_2 b (\hat{a}_z) \times \frac{\mu_o \mathbf{I}_1}{2\pi d} (-\hat{a}_x) = \frac{\mu_o b \mathbf{I}_2 \mathbf{I}_1}{2\pi d} (-\hat{a}_y) \text{-----(4)}$$

Thus, the total force is the sum of these forces and because the forces in the z-direction have the same magnitude and are opposite to each other, they are cancels each other. While the other two force are adding and gives:

$$\vec{F}_t = \vec{F}_1 + \vec{F}_2 + \vec{F}_3 + \vec{F}_4 = \vec{F}_2 + \vec{F}_4 = \frac{\mu_o b \mathbf{I}_1 \mathbf{I}_2}{2\pi} \left(\frac{1}{d+a} - \frac{1}{d} \right) \hat{a}_y$$

$$\vec{F}_t = \frac{4\pi \times 10^{-7} \times 0.5 \times 15 \times 10}{2\pi} \left(\frac{1}{0.1+0.2} - \frac{1}{0.1} \right) \hat{a}_y$$

$$\Rightarrow \Rightarrow \vec{F}_t = 1.5 \times 10^{-5} (-6.66) \hat{a}_y = -0.1 \hat{a}_y \text{ (mN)}$$